

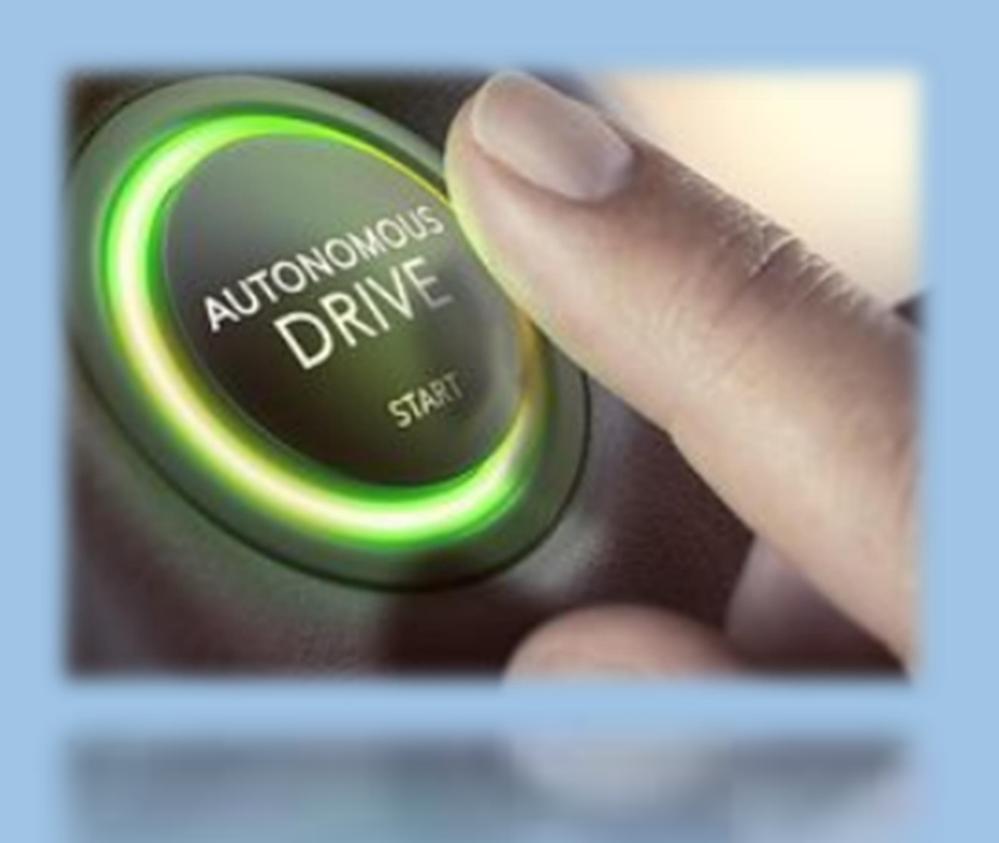
Aerial-Ground Cooperative Vehicular Networks

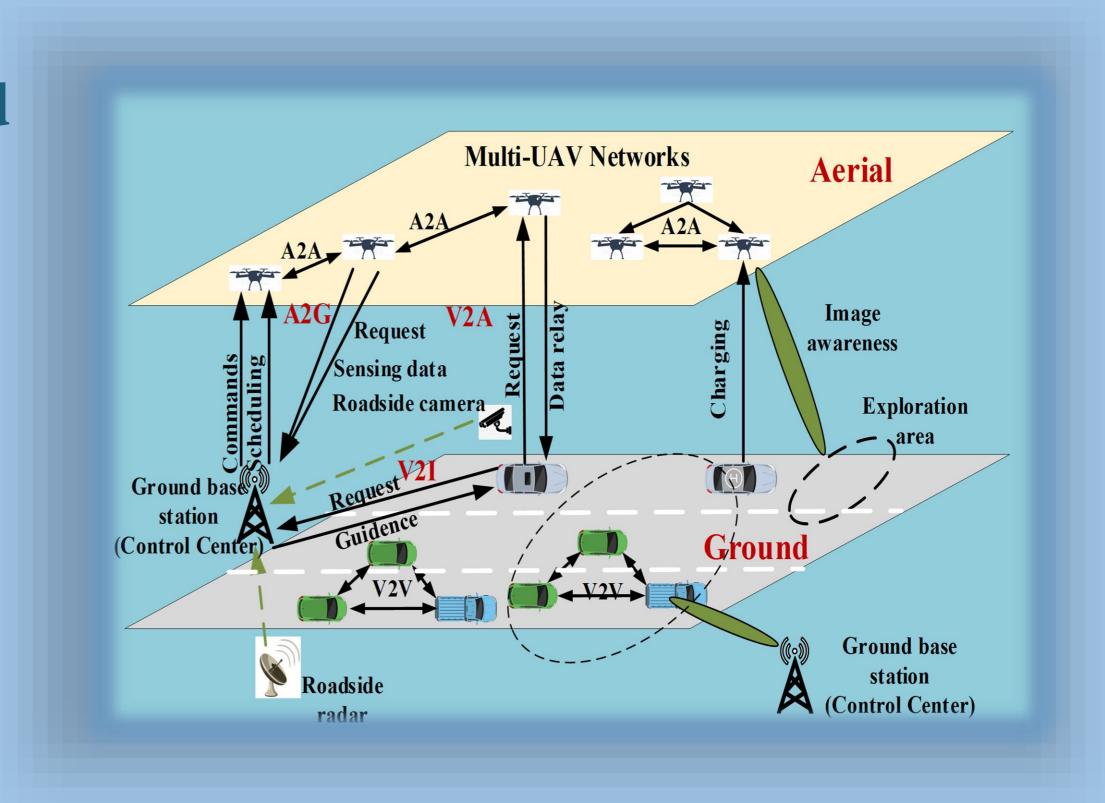
Xiao Liu, Yuanwei Liu and Yue Chen

School of Electronic Engineering and Computer Science, Queen Mary University of London

Autonomous driving has received remarkable attention both in the academia and industry.

- In the current autonomous driving systems, in-vehicle equipment (radars, cameras, CPU, and sensors) increases the cost of automated vehicles.
- Autonomous driving is able to improve our city life by being much more environmentally friendly, time saving and being much safer for the drivers and pedestrians alike.





- Multiple UAVs, forming an aerial subnetwork, aid the ground autonomous vehicles subnetwork by serving up-to-date information about the neighbor vehicle dynamics and other traffic information.
- UAVs can act as **intermediate relays** due to their flexible mobility when network partitions happen in the ground vehicular subnetwork.
- Reinforcement learning algorithm is invoked for obtaining the optimal motions of autonomous vehicles by exploring the environment in an iterative manner and by learning from their mistakes.

